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OVERVIEW

1. Introduction

2. Theoretical background

3. Methodology

4. Results and discussion

5. Conclusion

The 2009-paper survey a set of wonderful results of the research community providing EFFICIENT & STABLE ALGORITHMS to address SPARSITY-driven INVERSE PROBLEMS (with $J_0(\bar{x}), J_1(\bar{x})$) and their APPLICATIONS.

The message is

- if A has s columns then if $\bar{x} \in \mathbb{R}^n$ and $J_0(\bar{x}) < \frac{1}{2}(1 - \frac{s}{n})$ then \bar{x} is the unique solution to Problem (1)
- both greedy algorithms will solve Pr

A ROAD-MAP:

- MUSIC & Resolution of Echos

RO Schmidt (1979)

Bruckstein Shan Kailath (1985)

Optic Flow (2006) Nir, Bruckstein, Kimmel

Local Modeling (2007) Nir, Bruckstein

(2013) Shem-Tov, Rosman, Adir
Kimmel, Bruckstein

3 LEAST SQUARES

Savitzky Golay (1964)

Lancaster, Salkauskas (1981)

- NONLOCAL OVERPARAMETRIZED VARIATIONAL
method vs SPARSITY Based Solutions

Ginyos, Elad, Bruckstein

(2014-2020??)

MUSIC & ECHO RESOLUTION

$r(t)$ ←

$$r(t) = \sum_{i=1}^k s_i a(t - \theta_i) + m(t)$$

(noise)

we have

$$\begin{bmatrix} \vdots \\ a(\theta_k) \\ \vdots \end{bmatrix}$$

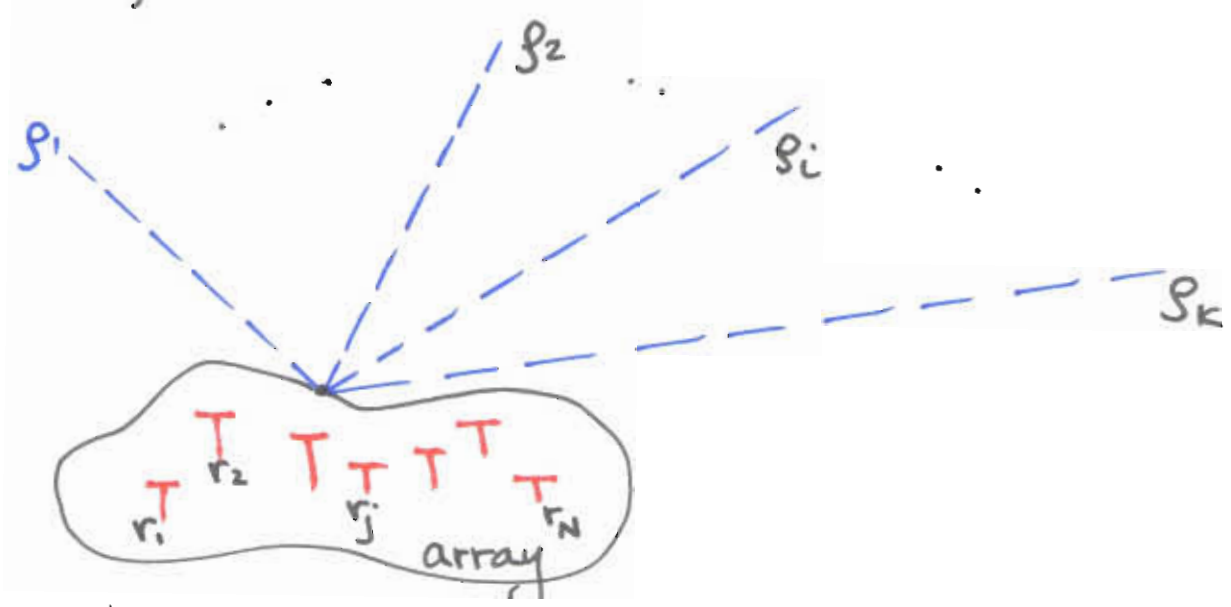
$$\dots a(t_N)$$

$$\begin{bmatrix} \vdots \\ \vdots \\ \vdots \\ s_1 \\ \vdots \\ s_2 \\ \vdots \\ \vdots \\ s_k \\ \vdots \end{bmatrix}$$

etized

a sparse vector with only k nonzero entries
Given \bar{r} estimate $\{\theta_1, \theta_2, \dots, \theta_k\}$.

We consider an antenna from radiation source



$$a(\theta_1) a(\theta_2) \dots a(\theta_k)$$

$$r_i = \underbrace{\begin{bmatrix} \vdots \\ \dots a(\theta_i) \dots \\ \vdots \end{bmatrix}}_{A_{N \times M}} \begin{bmatrix} \vdots \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

a long vector with only K nonzero entries.

The matrix A obeys (usually) from physical constraints or by design, that any N columns of it form a full rank square matrix, i.e. no column can be replaced by a linear combination of fewer than N others.

a fixed set of θ :

Then we can do:

- Estimate the autocorrelation matrix

$$\begin{aligned} \mathbb{R}_r &= E \bar{r} \bar{r}^T = A(\theta_1, \theta_2, \dots, \theta_k) E_{\mathbb{P}} E_{\mathbb{P}}^T A^T(\theta_1, \theta_2, \dots, \theta_k) + E_{nn} E_{nn}^T \\ &= A \cdot \mathbb{R}_{\mathbb{P}} A^T + \underbrace{\sigma_n^2 \mathbb{I}}_{\mathbb{R}_N} \end{aligned}$$

- From this the eigenvalues of \mathbb{R}_r will be:
 $N-K$ eigenvalues = σ_n^2 and K higher ones since $\mathbb{R}_{\mathbb{P}}$ is assumed to be a full rank matrix (i.e. the sources of echos or radiation are uncorrelated or at least not fully correlated)
from this we estimate σ_n^2 and compute $\mathbb{R}_r - \sigma_n^2 \mathbb{I}$

- Now $\mathbb{R}_r - \sigma_n^2 \mathbb{I}$ has $N-K$ zero eigenvalues with a nullspace spanned by $N-K$ orthonormal vectors $\{\bar{v}_{k+1}, \bar{v}_{k+2}, \dots, \bar{v}_N\}$.

- Hence we know that

$$(\mathbb{R}_r - \sigma_r \mathbb{I}) \underline{v}_j = \underline{0} \quad \text{for } j = k+1, k+2, \dots, N$$

$$\text{or } A \mathbb{R}_p A^T \underline{v}_j = 0$$

$$\Rightarrow \boxed{A^T \underline{v}_j = \underline{0}} \quad \text{for } j = k+1, k+2, \dots, N$$

Therefore $\langle a(\theta_i), \underline{v}_j \rangle = 0$ for $i = 1, 2, \dots, k$
 $j = k+1, k+2, \dots, N$

- Now search for all θ 's for which

$$\langle a(\theta), \underline{v}_j \rangle = 0 \quad (j = k+1, k+2, \dots, N)$$

by plotting for example the function

$$\Psi(\theta) = \frac{1}{\sum_{j=k+1}^M \langle a(\theta), \underline{v}_j \rangle^2}$$

and select the k places where $\Psi(\theta)$ peaks
 (theoretically it should become ∞ !).

WONDERFUL, ISN'T IT?



In the echos example radar engineers are taught to use the "optimal" matched filter to the signal $a(t)$. This filter correlates $r(t)$ with $a(t-\theta)$ for all θ 's in the range of interest and the response

$$\Psi(\theta) = \int_{\Omega_t} r(t) a(t-\theta) dt \quad (*)$$

provides estimates for θ_i 's as peaks of $\Psi(\theta)$.

(*) radar engineers are very happy with this because $\Psi(\theta)$ is the result of a convolution operator, readily implementable as a fixed time-invariant filter!

We can take this idea for the general case and compute for all $a(\theta)$ the inner products $\langle \bar{r}, a(\theta) \rangle = \Psi_{\bar{r}}(\theta)$

as the estimates for $\theta_1, \theta_2 \dots \theta_k$.

(The Thresholding Algorithm)

or we can also proceed as follows

1. for all $\{\theta\}$ compute

$$\langle \bar{r}, a(\theta) \rangle = \Psi_{\bar{r}}(\theta)$$

select the maximum value of $\Psi_{\bar{r}}(\theta)$

~ it provides θ_1 , then do

$$\bar{r} - \langle \bar{r}, a(\theta_1) \rangle a(\theta_1) \rightarrow \bar{r}^{\text{next}}$$

2. Now for all $\{\theta\} \neq \theta_1$ compute

$$\langle \bar{r}^{\text{next}}, a(\theta) \rangle = \Psi_{\bar{r}^{\text{next}}}(\theta)$$

select maximum value

~ it provides θ_2 then do

3.

as before

.....

OK

etc.

This is the

MATCHING PURSUIT ALGORITHM